# A CLASSICAL REALIZABILITY MODEL FOR A SEMANTICAL VALUE RESTRICTION



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## Program proving and proof programming in ML

```
type rec nat = [Z | S of nat]
val rec add : nat => nat => nat =
  fun n m ->
    match n with
    | Z -> m
    | S[n'] -> S[add n' m]
val addZN : (n : nat) => (add Z n == n) =
  fun n -> {}
val rec addNZ : (n : nat) => (add n Z == n) =
  fun n ->
    match n with
    | Z -> {}
| S[n'] -> addNZ n'
```

#### AN HOMOGENEOUS LANGUAGE

## Main features:

- call-by-value language with effects,
- extended type system for specification,
- proof as program (a single language).

Proofs can be composed as (and with) programs.

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This breaks the compositionality of proofs and programs.

## **ENCODING VALUE RESTRICTION**

Use two forms of judgements:  $\Gamma \vdash t : A$  and  $\Gamma \vdash_{val} v : A$ .

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$$\frac{\Gamma,\,x:A\vdash_{t}:B}{\Gamma,\,x:A\vdash_{val}\,x:A}^{Ax} \qquad \qquad \frac{\Gamma,\,x:A\vdash t:B}{\Gamma\vdash_{val}\,\lambda x\,t:A\,\Rightarrow\,B}^{\rightarrow_{t}}$$

$$\frac{\Gamma \vdash t : A \Rightarrow B \quad \Gamma \vdash u : A}{\Gamma \vdash t u : B} \rightarrow_{e}$$

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$$\frac{\Gamma \vdash t : A \Rightarrow B \quad \Gamma \vdash u : A}{\Gamma \vdash t u : B} \rightarrow_{e}$$

One more rule is required.

$$\frac{\Gamma \vdash_{\text{val}} \nu : A}{\Gamma \vdash \nu : A} \uparrow$$

#### RESTRICTED TYPE CONSTRUCTORS

$$\frac{\Gamma \vdash_{\mathsf{val}} \mathbf{v} : A \quad X \notin \mathsf{FV}(\Gamma)}{\Gamma \vdash_{\mathsf{val}} \mathbf{v} : \forall X \ A} \qquad \frac{\Gamma \vdash \mathsf{t} : \forall X \ A}{\Gamma \vdash \mathsf{t} : A[X \coloneqq B]} \lor_{\mathsf{e}}$$

# EQUIVALENCE AND SEMANTICAL VALUE RESTRICTION

With value restriction, some rules are restricted to values.

Idea: a term that is equivalent to a value may be considered a value.

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Informal proof:

$$\frac{\frac{\Gamma, t \equiv \nu \vdash t : A}{\Gamma, t \equiv \nu \vdash \nu : A} \quad X \notin FV(\Gamma)}{\frac{\Gamma, t \equiv \nu \vdash \nu : \forall X \ A}{\Gamma, t \equiv \nu \vdash t : \forall X \ A}}$$

## DERIVING THE RELAXED RULES

$$\frac{\Gamma, t \equiv \nu \vdash t : A}{\Gamma, t \equiv \nu \vdash \nu : A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : A}{\Gamma, t \equiv \nu \vdash_{val} \nu : A} \xrightarrow{X \notin FV(\Gamma)}_{\forall_e} \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv_{val} \nu : \forall X A}{\Gamma, t \equiv_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv_{val} \nu : \forall X A}{\Gamma, t \equiv_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv_{val} \nu : \forall X A}{\Gamma, t \equiv_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv_{val} \nu : \forall X A}{\Gamma, t \equiv_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv_{val} \nu : \forall X A}{\Gamma, t \equiv_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv_{val} \nu : \forall X A}{\Gamma, t \equiv_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv_{val} \nu : \forall X A}{\Gamma, t \equiv_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv_{val} \nu : \forall X A}{\Gamma, t \equiv_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv_{val} \nu : \forall X A}{\Gamma, t \equiv_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv_{val} \nu : \forall X A}{\Gamma, t \equiv_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv_{val} \nu : \forall X A}{\Gamma, t \equiv_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv_{val} \nu : \forall X A}{\Gamma, t \equiv_{val} \nu : \forall X A} = \frac{\Gamma, t \equiv_{val} \nu : \forall X A}{\Gamma, t \equiv_{val} \nu : \forall X A}$$

## KRIVINE MACHINE

```
v, w := x | \lambda x t | C[v] | \{l_i = v_i\}_{i \in I}
t, u := \alpha | v | tu | \mu \alpha t | [\pi]t | v.l | case v of [C_i[x] \rightarrow t_i]_{i \in I}
\pi := \alpha | v \cdot \pi | [t] \pi
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     \pi := \alpha \mid \nu \cdot \pi \mid [t] \pi
                                                   tu*\pi > u*[t]\pi
                                                 v*[t]\pi > t*v\cdot\pi
                                            (\lambda x t) * \nu \cdot \pi > t[x \leftarrow \nu] * \pi
                                                 \mu \alpha t * \pi > t[\alpha \leftarrow \pi] * \pi
                                                  [\pi]t*o > t*\pi
           case C_k[v] of [C_i[x] \to t_i]_{i \in I} * \pi > t_k[x \leftarrow v] * \pi
                                   \{l_i = v_i\}_{i \in I} l_k * \pi > v_k * \pi
```

Three levels of interpretation:

- raw semantics [A],

$$\begin{split} \big[\![\{l_i:A_i\}_{i\in I}\big]\!] &\coloneqq \big\{\!\{l_i=\nu_i\}_{i\in I}\mid \forall i\in I, \nu_i\in [\![A_i]\!]\big\} \\ & [\![\forall X\;A]\!] \coloneqq \cap_{\Phi\subseteq\mathscr{V}/\equiv} \big[\![A[X\coloneqq\Phi]]\!] \\ & [\![t\equiv u]\!] \coloneqq \big[\![\{\}]\!] \text{ when } t\equiv u \text{ and } \emptyset \text{ otherwise} \end{split}$$

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- raw semantics [A],
- falsity value  $\llbracket A \rrbracket^{\perp} = \{ \pi \mid \forall \nu \in \llbracket A \rrbracket, \nu * \pi \in \bot \},$

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- truth value  $\llbracket A \rrbracket^{\perp \perp} = \{t \mid \forall \pi \in \llbracket A \rrbracket^{\perp}, t * \pi \in \bot \}.$

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# ADEQUACY LEMMA

# **Theorem** (Adequacy Lemma):

- if t is a term such that  $\vdash$ t: A then t  $\in$   $\llbracket A \rrbracket^{\perp \perp}$ ,
- if  $\nu$  is a value such that  $\vdash_{val} \nu : A$  then  $\nu \in \llbracket A \rrbracket$ .

Intuition: a typed program behaves well (in any well-typed evaluation context).

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This provides a semantical justification to the rule  $\frac{\Gamma \vdash_{\text{val}} v : A}{\Gamma \vdash v : A} \uparrow$ .

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#### SEMANTICAL VALUE RESTRICTION

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This provides a semantical justification to the rule  $\frac{\Gamma \vdash_{\text{val}} v : A}{\Gamma \vdash v : A} \uparrow.$ 

We need to have  $[\![A]\!]^{\perp\perp} \cap \mathscr{V} \subseteq [\![A]\!]$  to obtain the rule  $\frac{\Gamma \vdash \nu : A}{\Gamma \vdash_{val} \nu : A} \downarrow.$ 

With this rule we can derive relaxed typing rules.

$$\frac{\frac{\Gamma, t \equiv \nu \vdash t : A}{\Gamma, t \equiv \nu \vdash \nu : A}}{\frac{\Gamma, t \equiv \nu \vdash_{val} \nu : A}{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X \not\in FV(\Gamma)}} \times_{\forall_e} \frac{\frac{\Gamma, t \equiv \nu \vdash_{val} \nu : \forall X \not A}{\Gamma, t \equiv \nu \vdash \nu : \forall X \not A}}{\frac{\Gamma, t \equiv \nu \vdash \nu : \forall X \not A}{\Gamma, t \equiv \nu \vdash t : \forall X \not A}}$$

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We will have  $\delta_{v,w} * \pi > v * \pi$  if and only if  $v \not\equiv w$ .

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# Idea of the proof:

- suppose  $v \notin [A]$  and show  $v \notin [A]^{\perp \perp}$ ,
- we need to find  $\pi$  such that  $v*\pi \notin \mathbb{L}$  and  $\forall w \in \llbracket A \rrbracket, w*\pi \in \mathbb{L}$ ,
- we can take  $\pi = [\lambda x \, \delta_{x,v}] \varepsilon$ ,
- $\ \nu * [\lambda x \, \delta_{x,\nu}] \varepsilon > \lambda x \, \delta_{x,\nu} * \nu . \varepsilon > \delta_{\nu,\nu} * \varepsilon,$
- $w*[\lambda x \delta_{x,v}]\varepsilon > \lambda x \delta_{x,v}*w.\varepsilon > \delta_{w,v}*\varepsilon > w*\varepsilon$ .

# STRATIFIED REDUCTION AND EQUIVALENCE

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We need to rely on a stratified construction of the two relations

$$(\twoheadrightarrow_{i}) = (\gt) \cup \{(\delta_{\nu,w} * \pi, \nu * \pi) \mid \exists j < i, \nu \not\equiv_{j} w\}$$
$$(\equiv_{i}) = \{(t, u) \mid \forall j \leq i, \forall \pi, \forall \sigma, t \sigma * \pi \Downarrow_{j} \Leftrightarrow u \sigma * \pi \Downarrow_{j}\}$$

We then take

$$(\twoheadrightarrow) = \bigcup_{\mathfrak{i} \in \mathbb{N}} (\twoheadrightarrow_{\mathfrak{i}}) \qquad (\equiv) = \bigcap_{\mathfrak{i} \in \mathbb{N}} (\equiv_{\mathfrak{i}})$$

## CURRENT AND FUTURE WORK

# Subtyping without coercions:

- useful for programming (modules, classes...),
- provide injections between types for free,
- interprets  $\vdash A \subseteq B$  as  $\llbracket A \rrbracket \subseteq \llbracket B \rrbracket$  in the semantics.

# Implementation (in progress):

- the types  $\mu X A$  and  $\nu X A$  will be handled by subtyping,
- we need to extend the language with a fixpoint,
- termination needs to be ensured to preserve soundness.

# Theoretical investigation (for later):

- can we use  $\delta_{v,w}$  to realize new formulas,
- how do we encode real maths in the system?